CHAPTER X TEM TECHNIQUES FOR CHARACTERIZING DISLOCATIONS

10.1 Transmission Electron Microscopy

Transmission Electron Microscopy (TEM) is a powerful tool for materials science, particularly for characterizing crystal defects such as dislocations. Dislocations are line defects within a crystal that can drastically alter a material's properties, including its mechanical strength and electrical behavior. The first in-situ measurements of dislocations and dislocation motion in a Transmission Electron Microscope (TEM) were groundbreaking because they provided direct, real-time visualization of these phenomena at the atomic scale. Early works, such as those by Hirsch, Bollmann, and others, utilized darkfield and brightfield imaging modes to identify and observe dislocations. The resolution was limited, but they could still capture dislocation networks and estimate their density. This capability allowed researchers to observe how dislocations, which are line defects in the crystal structure, behave under various conditions like mechanical stress, thermal activation, and other environmental factors.

The development of weak-beam dark-field (WBDF) imaging further improved the ability to visualize and analyze dislocations by enhancing contrast. This technique helped researchers study the fine structure of dislocations and understand their core configurations and motion mechanisms. Properly implementing the WBDF and analyzing these defects requires a deep understanding of diffraction contrast mechanisms, which can be described by the Howie-Whelan equations. As such, this chapter will introduce the Howie-Whelan equations and explain how they are used to characterize dislocations' line direction and Burger's vector using brightfield, dark-field, and weak-beam imaging techniques.

In addition to these diffraction contrast imaging techniques, this chapter will discuss modern TEM techniques, such as aberration-corrected high-resolution TEM (HRTEM), scanning TEM (STEM), and in-situ mechanical testing, which have enabled even more precise and detailed observations of dislocation behavior. These methods allow scientists to analyze dislocations at near-atomic resolution, track their motion under varying environmental conditions, and measure their interactions with other microstructural features.

10.1.1 A Brief History and Background

The fifth Solvay Conference on Physics, held in 1927 and attended by some of the most prominent minds, ushered in a new science and quantum mechanics theory era. The subject title of the conference was simple: Electrons and Photons. One of those famous attendees was the French physicist Louis de Broglie. He postulated that electrons have a wave behavior, a fundamental tenant of quantum mechanics underlying the wave-particle duality concept. However, these ideas were still controversial and were not widely adopted or proven in the 1930s. Ernst Ruska, a clever German engineer and one of the pioneer inventors of the transmission electron microscope (TEM), took note. In a speech at his Nobel prize award ceremony in 1986, Ruska famously said the following,

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"The resolution limit of the light microscope due to the length of the light wave which had been recognized 50 years before by Ernst Abbe and others could, because of lack of light, not be important at such magnifications. Knoll and I simply hoped for extremely low dimensions of the electrons. As engineers we did not know yet the thesis of the "material wave" of the French physicist de Broglie that had been put forward several years earlier (1925). Even physicists only reluctantly accepted this new thesis. When I first heard of it in the summer 1931, I was very much disappointed that now even at the electron microscope the resolution should be limited again by a wavelength (of the "Materiestrahlung"). I was immediately heartened, though, when with the aid of the de Broglie equation I became satisfied that these waves must be around five orders of magnitude shorter in length than light waves. Thus, there was no reason to abandon the aim of electron microscopy surpassing the resolution of light microscopy."

As de Broglie noted from Einstien's theory of special relativity, the calculation of a fast electron's wavelength (λ) having energies greater than 50keV must involve a relativistic correction as follows,

$$\lambda = \frac{h}{\left[2m_0 eV \left(1 + \frac{eV}{2m_0 c^2}\right)\right]^{1/2}}$$
10.1

Indeed, the short wavelength of fast electrons on a couple of picometers provides the resolution to observe atoms. Table 1 lists the electron wavelengths and velocities for different operating voltages in scanning and transmission electron microscopes.

Table 10.1 Calculation of electron wavelengths for different electron energies

Electron charge (e)	-1.602 x 10 ⁻¹⁹ C	non relativistic (<50keV)
1 eV	1.602 x 10 ⁻¹⁹ J	$\lambda = \frac{h}{h}$
Electron rest mass (m _o)	9.109 x 10 ⁻³¹ kg	$\lambda = \frac{1}{(2 m_0 eV)^{1/2}}$
Electron rest energy (m _o c ²)	511 keV	Relativistic correction
Kinetic energy (charge x tension)	1.602 x 10 ⁻¹⁹ Nm (per 1 volt)	1
Plank's constant (h)	6.626 x 10 ⁻³⁴ N-m-s λ	$=$ $\frac{h}{1}$
1 Ampere	1 C/sec	$\begin{bmatrix} 2 & eV \end{bmatrix}^{\frac{1}{2}}$
Light speed in vacuum (c)	2.998 x 108 m/sec	$\left[2m_0eV\left(1+\frac{eV}{2m_0c^2}\right)\right]^{\frac{1}{2}}$
		_

Accelerating voltage [KV]	Nonrelativistic λ [nm]	Relativistic λ [nm]	Mass [x m _o]	Velocity [x 10 ⁸ m/s]
1	0.03879	0.03878	1.002	0.13
10	0.01227	0.01221	1.02	0.42
80	0.00434	0.00418	1.157	1.1
200	0.00274	0.00251	1.391	1.59
300	0.00224	0.00197	1.587	1.82
1000	0.00123	0.00087	2.957	2.44

10.1.2 Spatial Resolution of TEMs

Spatial resolution is typically defined by the ability to distinguish between two closely spaced points or arry diffraction disks, referred to as the diffraction-limited resolution. For conventional light Physics of materials

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microscopes, the resolution is fundamentally limited by the wavelength of visible light. The diffraction-limited resolution can be defined by the Raleigh criterion,

$$d = 0.61 \frac{\lambda}{n \sin \theta} = 0.61 \frac{\lambda}{\beta}$$

where n is the refractive index, λ is the wavelength, and β is the collection angle (inversely related to the numerical aperture), and indicates that short wavelengths and high collection angles are essential for better resolution. As such, the resolution of visible light optical microscopes was capped at approximately 200 nanometers (nm), restricting the ability to observe structures smaller than this threshold.

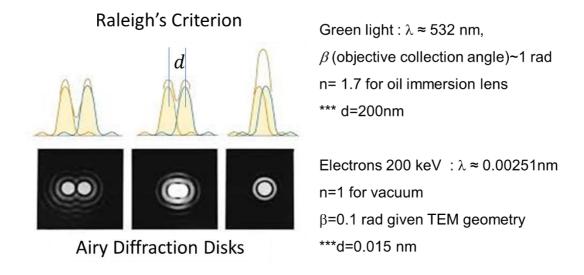


Figure 10.1 Schematic of Raleigh criterion and comparison between optical and electron microscope resolution

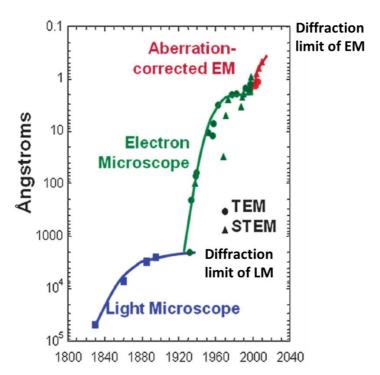


Figure 10-2: Plot of the evolution in microscope spatial resolution over 200 yrs.

took decades of technological development to improve the quality of magnetic lenses and electronics of the TEM to a sufficient level to achieve atomic resolution. Yet, due to the imperfections of the magnetic lenses (e.g., their spherical and chromatic aberrations), the achievable resolution was still a factor of 100 less than the diffraction limit (15 pm, as shown in Figure 10-1). The invention of aberration correctors monochromators and (improved electron sources) significantly improved the resolution, providing picometer precision for determining the samples' structure (Figure 10-2). The adoption widespread of aberration correction in commercial TEMs has dramatically impacted the field of nanotechnology, allowing to characterize the atomic-scale defects and

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impurities in nanomaterials crucial for advancing their processing technologies and implementation in devices. Likewise, these technological improvements and new sensitive detectors in cryo-electron microscopy have allowed for solving complex protein structures that cannot be crystallized and studied by standard Synchrotron X-ray scattering techniques. Electron microscopy has become an essential characterization tool for research in all physical sciences disciplines.

10.1.3 TEM construction

The Transmission Electron Microscope consists of 5 essential parts: (1) Electron gun, (2) Condenser lens, (3) Objective Lens, (4) Intermediate lenses, and (5) Detectors (See Figure 10-3).

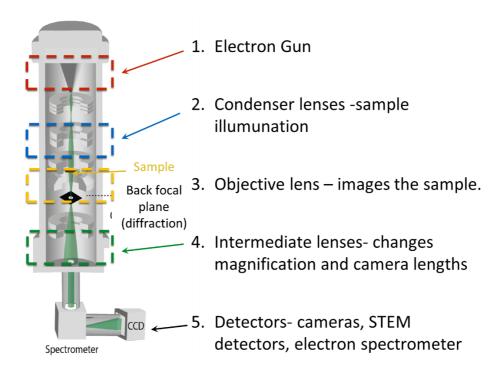


Figure 10-3: Basic Schematic TEM

The electron gun comprises the electron source, which can be a field emission or thermionic, and the linear accelerator section consisting of a sequence of anode plates that can typically accelerate the electrons in the range of 30-300keV. Cold field emission guns (C-FEGs) use a sharp tungsten tip cooled to enhance electron emission with minimal thermal spread, providing high brightness and spatial coherence ideal for high-resolution imaging. Schottky field emission guns (S-FEGs) combine thermally assisted field emission with a ZrO₂-coated tungsten tip, offering stability, longer lifetime, and high brightness, though with a slightly broader energy spread than C-FEGs. Both are suited for high-resolution applications, but S-FEGs are often preferred for their practical stability in routine operations.

Conversely, **thermionic guns** emit electrons through thermal excitation and have lower spatial coherence and higher energy spread than FEG guns. In TEM, thermionic guns typically have brightness values around $10^5 - 10^6$ A/cm²·sr, considerably lower than field emission guns (FEGs), which can reach brightness levels above $10^8 - 10^9$ A/cm²·sr. However, thermionic guns offer advantages over FEGs, including more straightforward design, greater stability over time, longer operational lifetimes, and lower maintenance requirements, making them more cost-effective and robust for routine imaging applications where ultra-high resolution is not essential.

The condenser lens system controls the intensity and convergence of the electron beam on the sample. It typically consists of multiple electromagnetic lenses that shape and focus the beam emitted by the electron source, such as a thermionic gun or a field emission gun. By adjusting the condenser lenses, users can change the beam's brightness and spot size, allowing for fine-tuning of the electron dose on the sample. This control is crucial in TEM, as it affects the resolution, contrast, and amount of detail visible in the final image, e.g., for dislocation imaging. In addition, the condenser lenses enable switching between different illumination modes, such as parallel illumination for high-resolution imaging and convergent beam illumination for analytical techniques like electron diffraction.

The objective lens forms the specimen's magnified image and its corresponding diffraction pattern. It focuses the electron beam after interaction with the specimen, directing both transmitted and scattered electrons to converge at specific planes within the optical system: the image plane for real-space imaging and the back focal plane where the diffraction pattern forms, providing information on the sample's crystal structure and orientation., the sample is positioned in the object or eucentric plane of the objective lens, the plane where the sample can be tilted about its center without shifting the image or diffraction pattern, to reduce aberrations and obtain high spatial resolution. Proper alignment of the sample at the eucentric height allows for consistent focusing and easier analysis, especially when working with tilted samples in high-resolution or diffraction studies.

The intermediate and projection lens sections are crucial for forming and magnifying the electron image. The intermediate lens system adjusted image magnification and the camera length of the diffraction pattern. The projection lens then further magnifies the image on a fluorescent screen or camera. TEMs often incorporate three intermediate lenses, which correct the image rotation due to changes in the electrons' spiral trajectory within the focusing magnetic field of the lenses that can occur with varying magnifications or imaging settings. Knowing the image rotation between real-space and reciprocal space lattice vectors (diffraction imaging conditions \vec{g}) is essential for determining the dislocation image contrast the Burger's vector (\vec{b}) using the invisibility criterion discussed in section §10.2.

Morden TEMs have many detectors that provide comprehensive information about a sample's structure, composition, and electronic properties (discussed in the next section), such as,

STEM Detectors (Brightfield, Dark-Field, and HAADF): In scanning transmission electron microscopy (STEM) mode, detectors like brightfield, dark-field, and high-angle annular dark-field (HAADF) are used to capture images based on how electrons interact with the sample. Brightfield detectors utilize unscattered electrons to highlight dense areas as darker regions, while dark-field detectors use scattered electrons to observe specific structural details. HAADF detectors, capturing electrons scattered at high angles, provide high-contrast images sensitive to atomic number, making them ideal for atomic-resolution imaging and compositional mapping.

Electron Energy Loss Spectroscopy (EELS) Detectors: EELS detectors measure the energy lost by electrons as they pass through the sample, providing detailed information about electronic structure and bonding. This technique is particularly valuable for analyzing light elements and subtle structural changes within the sample.

Charge-Coupled Device (CCD) Detectors: CCD detectors are commonly used in TEMs for direct digital imaging, converting electron interactions with the sample into electronic signals. Known for their high sensitivity and broad dynamic range, CCDs are ideal for capturing high-quality, high-resolution images, especially in low electron dose conditions.

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Complementary Metal-Oxide-Semiconductor (CMOS) Detectors: CMOS detectors, an alternative to CCDs, are known for their faster readout speeds and lower power consumption. Often used in applications requiring rapid image acquisition, CMOS detectors are robust and increasingly common in modern TEMs for high-resolution imaging with real-time analysis capabilities.

10.1.3 Interactions of fast electrons with TEM samples

Fast electrons are not only useful for probing the atomic structure of samples; they can be used to characterize a material's chemistry and electronic structure on the atomic scale. The interaction of high-energy electrons with matter involves complex scattering processes. It produces many different scattered electron signals and secondary particles, such as plasmons, phonons, X-rays, and visible light. Figure 10-4 illustrates some of the scattered and secondary produced in the TEM.

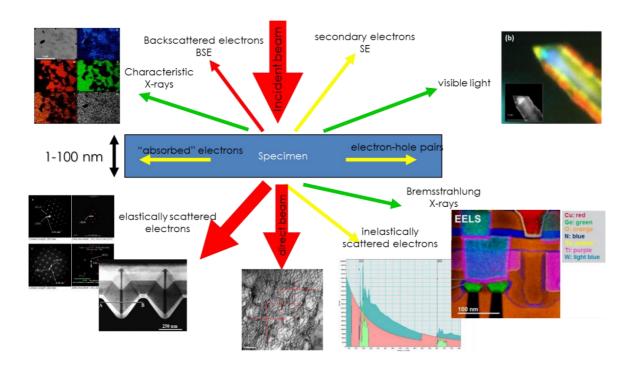


Figure 10-4: Schematic showing the imaging modes and sample characterization using the primary and secondary scattered signals produced by high-energy electron interactions with a thin TEM sample.

Typical TEM samples are sufficiently thin for electron transparency, on the order of 10-100nm. The interactions of fast electrons with materials can be subdivided into elastic and inelastic scattering. Elastic scattering can be described as electrons that do not transfer energy (elastic), while inelastic electrons lose significant energy due to scattering processes in the sample. We can also refer to the scattering process as coherent if the phase of the scattered electron waves is in phase. In contrast, incoherently scattered electrons have no phase relation among them. Here, we use the definitions of coherence and energy transfer (elastic and inelastic scattering processes) to describe different TEM modes and how these scattered signals can be used to characterize materials, and this chapter focuses on diffraction and diffraction contrast imaging.

10.1.4 Diffraction and Imaging Modes

Since their invention, TEMs have been designed to operate in two distinct modes: imaging and diffraction. Bragg diffraction is a coherent, elastic scattering process in which the electron waves

scattered from a periodic lattice constructively and destructively interfere (phase coherence). The resulting patterns of coherently scattered electrons have intensities that quantitatively define the sample's atomic structure. The reciprocal lattice resolution of diffraction patterns is a measure of the transverse coherence of the electron beam; e.g., a typical modern 200kV TEM can have a transverse coherence length of a few μm .

With such resolution, electron diffraction can probe, for example, phase changes, crystallinity, crystal orientation, local charge states (e.g., charge density waves), phonon resonances, and magnetic ordering, amongst other periodic ordered structural characteristics of the sample. Figures 10-5 a and 10-5 b compare the difference between diffraction from a single crystal and a random polycrystal. The spot pattern of Figure 10-4a corresponds with the unit cell structure and orientation relative to the electron beam, the so-called zone axis, while the ring pattern of the polycrystal results for the small crystals with random orientations, similar to patterns of in X-ray diffraction Debye camera geometries. However, the diffracted electron intensities are challenging to interpret and require simulations (using Bloch wave theory) to determine quantitatively and account for dynamical elastic scattering effects.

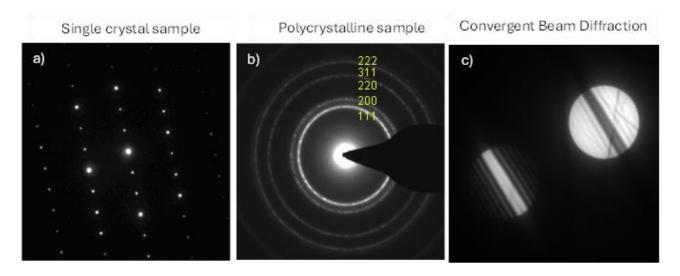


Figure 10-5: Typical diffraction patterns of TEM samples. a) A spot pattern formed single crystal in which pattern and its intensity relate to orientation and unit cell of the crystal, b) Debye ring patterns are generated for randomly oriented polycrystals, c) convergent beam electron diffraction (CBED) patterns exhibit multiple (dynamical) elastic scattering and coherent inelastic scattering of crystal atomic planes (excess and deficient lines) of the sample.

Since making TEM samples a few nanometers thick is challenging, most samples typically exceed the mean free path for elastic scattering, resulting in plural scattering. The repeated diffraction of electron waves due to atomic planes' periodic spacing causes constructive and destructive interference that depends on the sample's lattice and thickness, causing a resonant intensity profile with sample thickness. For example, in the convergent beam diffraction pattern of Figure 5c, there is a thick dark line (called deficient line) in the bright disk and a thick white line (excess) in the dark disk surrounded by multiple lines, which diminish in intensity. The diameter of the disks corresponds to the convergence angle, and the spacing between them is associated with the Bragg angle. The intensity in the disk consists of both incoherent scattering from all orientations and the excess and deficient lines resulting from coherent inelastic scattering from crystallographic planes (hkl). The intensity profile of the spots depends on the diffraction condition in relation to the Ewald's sphere (see Figure 10-5 a).

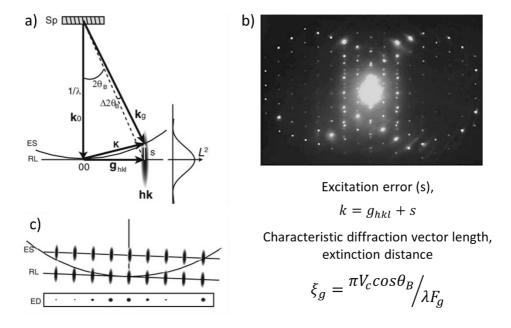


Figure 10-6: a) Schematic explaining the Ewald sphere construction in transmission electron diffraction and excitation error, b) Diffraction pattern showing rings of bright diffraction spot where Ewald sphere intercepts the reciprocal lattice, c) 2-D schematic showing how Ewald Sphere cuts through the relrods (reciprocal lattice rods of intensity).

The Ewald sphere (ES) is a geometrical construction used to determine which lattice planes satisfy the Bragg condition for diffraction. The radius of the Ewald sphere is inversely proportional to the electron wavelength, e.i., increases with increasing electron energy, and is centered at the origin of the reciprocal lattice ((000) diffraction spot). A lattice reflection, \vec{g} , intersects the sphere if the Bragg condition is met, resulting in diffracted beams and spots. However, due to the high energy of electrons (and hence their short wavelength) in TEM, the Ewald sphere is nearly flat, as seen in Figure 6, enabling diffraction from multiple crystallographic planes simultaneously.

The excitation error (*s*) quantifies the deviation of a reciprocal lattice point from the exact Ewald sphere surface and is given by:

$$s = \vec{k} - \overrightarrow{g_{hkl}}$$
 10.3

where \vec{k} is the wave vector of the incident beam. If s=0, the lattice plane satisfies the Bragg condition exactly; if $s \neq 0$, the plane is slightly off-Bragg condition, resulting in reduced diffracted intensity. Figure 10-6 c illustrates the concept the *s* corresponds to ES cutting through the ellipsoidal intensity distribution diffraction reflections (\vec{g}) and produce intensity variations in diffraction spots.

The extinction distance (ξ_g) represents the characteristic distance over which the electron beam exchanges intensity between the transmitted and diffracted beams due to multiple scattering in the crystal. It is a measure of the interaction strength between the electron wave and the crystal lattice planes and is given by:

$$\xi_g = \frac{\pi V_c cos\theta_B}{\lambda F_g}$$
 10.4

where V_c is the unit cell volume, θ_B is the Bragg angle, λ is the electron wavelength, and F_g is the structure factor. When the crystal thickness approaches or exceeds the extinction distance, dynamical effects become significant, leading to complex intensity distributions in the diffraction pattern. The extinction distance also influences the spread of diffraction spots in reciprocal space and affects the observed diffraction contrast, particularly in thicker crystals. This interplay is critical for Physics of materials

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understanding diffraction in both kinematical and dynamical regimes and how we interpret the dislocation image contrast and character.

The diffraction patterns are generated in the back focal plane of the objective lens that forms the sample's high-resolution image (Figure 10-3). Changing the lens currents of the intermediate post-objective lens system changes the magnification and diffraction camera length. Inserting an aperture in the back focal plane to select and omit different diffracted beams allows the formation of an image exhibiting contrast associated diffraction and structural information about the sample, so-called diffraction contrast imaging, commonly referred to as Brightfield and Dark-field images. Figure 7 shows an example of brightfield and dark-field imaging. This imaging technique is typically described as semi-coherent. Brightfield images hold information about morphology, grain size, and defect structures, while dark-field imaging can be used to correlate crystalline phase, orientation, and defect structures to grain morphologies and their distribution with the microstructure. Such techniques are powerful characterization tools to explore phase transitions, defect, and their dynamics, as will be described later.

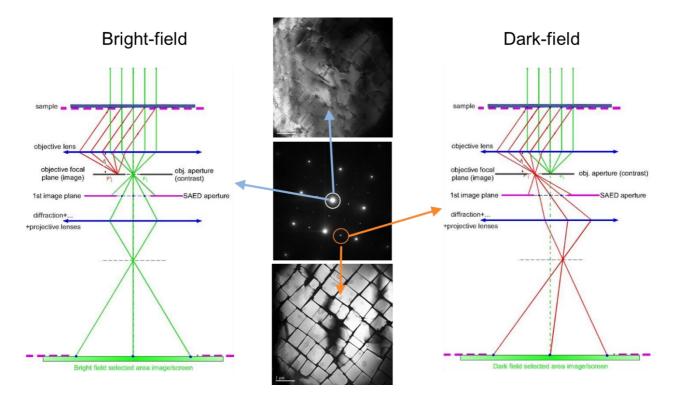


Figure 10-7: Diffraction contrast imaging using an objective aperture located in the back focal plane to form images from different scattering electron beams from the sample.

10.2 Howie Whelan Equations

The Howie-Whelan equations are fundamental to understanding electron diffraction contrast in TEM, particularly for defects like dislocations. They describe the interaction between an electron wave and a crystalline material using a two-beam approximation. The equations are derived from the Schrödinger equation, which governs the propagation of electrons as wave functions through a periodic potential.

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10.2.1 Kinematical and Dynamical Diffraction

Kinematical Diffraction Contrast theory assumes that only two beams—one direct and one diffracted—are considered, forming the basis for the two-beam condition. Figure 8 shows diffraction two-beam conditions in which various \vec{g} diffraction spots are excited in strong diffraction conditions.

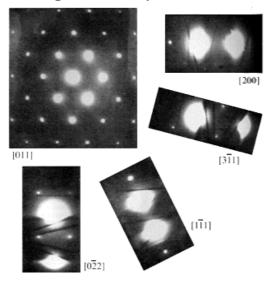


Figure 10-8: Different Two-Beam conditions produced by tilting the sample away from [011] zone axis, the bracketed Miller indices represent different \vec{g} vectors, which are used for dislocation analysis.

This model assumes single scattering, meaning only one scattering cycle influences the intensity, with minimal absorption, so that $I_{trans} = 1 - I_{diff}$. The intensity of the diffracted beam, I_{diff} , can be described by the equation:

$$I_{diff} = \frac{\sin^2(\pi zs)}{\xi_a s^2}$$
 10.5

where z is the thickness of the crystal, s is the excitation error, and ξ_g is the extinction distance given by equation 10-8.

In Dynamical Diffraction Contrast conditions, multiple scattering events are significant, where electrons undergo repeated diffraction interactions between lattice planes, making this model suitable for thicker samples. Unlike the simple single scattering in the kinematical model, dynamical diffraction involves more complex interactions, where the electron waves diffract multiple times, resulting in enhanced contrast and more intricate interference patterns. Dynamical scattering contrast around defects combined with its nanometer-scale image resolution has made Transmission Electron Microscopy a unique and invaluable tool for characterizing dislocations.

Thickness fringes are a specific manifestation of dynamical diffraction contrast, which arises due to variations in crystal thickness in regions of strong diffraction. Thickness fringes occur due to the interference between transmitted and diffracted beams, where the crystal thickness and the excitation conditions modulate the phase relationship. For example, in the wedge-shaped sample shown in Figure 10-9, dark fringes appear with multiples of 0.5 of the extinction distance, ξ_g . These thickness fringes are particularly pronounced in areas with structural irregularities, such as stacking faults, dislocation, grain boundaries, and phase boundaries, where localized changes in the amplitude and phase of the electron wave occur.

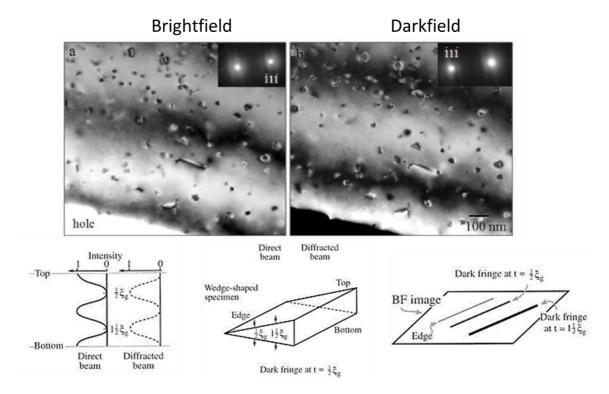


Figure 10-9: Example of thickness fringes that arise from the constructive and destructive interference from dynamical or multiple scattering events in which dark and bright fringes appear at multiples of the extinction distance in wedge shape TEM sample. The speckle-like contrast occurs due to the strain fields of small dislocation loops.

These multiple "dynamical" scattering effects due to thickness variations are influenced by the crystal's internal strain and lattice distortions, and contrast and fringes appearing around defects due to their localized strain fields can be used to visualize their detailed structures, e.g., size, crystallography, and a dislocation Burger's vector.

Diffraction contrast is highly sensitive to crystal imperfections, such as stacking faults, grain boundaries, translation boundaries, phase boundaries, and stepped surfaces. These defects introduce localized distortions in the crystal lattice, leading to variations in the amplitude and phase of the electron wave as it passes through the material. The resulting interference patterns, caused by constructive and destructive interference, produce fringe patterns in the diffraction contrast image, which reveal detailed information about the nature and distribution of these defects.

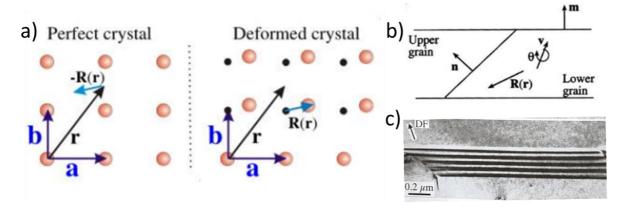


Figure 10-10: a) and b) schematic showing the lattice distortion and translation vector leading to a change in the local potential and to dynamical scattering effects such as the fringes in d) a darkfield TEM image of a stacking fault image with two beam condition.

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For example, the potential of perfect can be given by the following expression,

$$V(r) = \sum_{g} V_g e^{2\pi i g \cdot r}$$
 10.6

where g is reciprocal lattice vectors, and $g \cdot r$ represents the periodicity of the crystal lattice. For a crystal with a defect, the potential $V_{def}(r)$ can be expressed as a sum over the reciprocal lattice vectors g, incorporating a phase factor that reflects the defect's effect on the crystal structure:

$$V_{def}(r) = \sum_{g} V_g e^{2\pi i g \cdot [r - R(r)]}$$
 10.7

where V_g is the amplitude of the potential associated with the lattice planes, and r - R(r) denotes the position of the defect. This equation illustrates how translations and rotations between different crystal regions can cause periodic variations in the electron wave amplitude, leading to the fringe patterns observed in brightfield and dark-field imaging modes. The appearance of the stacking fault in Figure 10-10 d) depends on the thickness and two beam diffraction conditions. These patterns provide essential insights into the structural irregularities within the crystal, allowing researchers to study the nature of the defects and the associated lattice distortions.

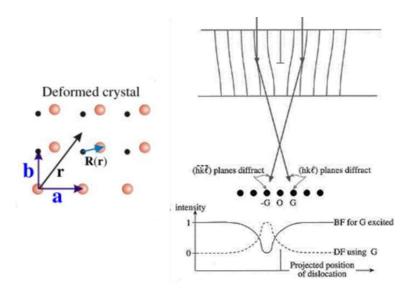


Figure 10-11 Schematic showing how the lattice distortion around a dislocation core leads to increased diffracted signals, R(r) in this case is the Burger's vector

10.2.2 Using the Howie-Whelan equations to interpret dynamical diffraction contrast around defects

For a crystal with a dislocation, the local lattice strain field alters the phase and amplitude of the transmitted and diffracted electron beams. In the two-beam case, where only the transmitted beam and one strong diffracted beam are considered, the equations are,

$$d\phi_o = \left\{ \frac{\pi i}{\xi_g} \phi_g e^{-2\pi i \mathbf{K} \cdot \mathbf{r}} + \frac{\pi i}{\xi_o} \phi_o \right\} dz \text{ and } d\phi_g = \left\{ \frac{\pi i}{\xi_g} \phi_o e^{2\pi i \mathbf{K} \cdot \mathbf{r}} + \frac{\pi i}{\xi_o} \phi_g \right\} dz$$
 10.8

where ϕ_o and ϕ_g are the amplitudes of the transmitted and diffracted beams, respectively, z is the direction of propagation of the electron beam through the crystal, ξ_g and ξ_o the extinction distances

of the diffracted and transmitted beams given by equation 10.8, and $K \cdot r$ is the scattering of the electron wave in the periodic crystal.

The amplitudes of ϕ_g and ϕ_o are coupled and change with propagation in the sample. Solving these coupled differential equations gives the intensity distribution of the transmitted and diffracted beams. The interaction of these beams results in the characteristic diffraction contrast observed in TEM images.

$$\frac{d\phi_o}{dz} = \left\{ \frac{\pi i}{\xi_g} \phi_g e^{2\pi i s z} + \frac{\pi i}{\xi_o} \phi_o \right\} \text{ and } \frac{d\phi_g}{dz} = \left\{ \frac{\pi i}{\xi_g} \phi_o e^{-2\pi i s z} + \frac{\pi i}{\xi_o} \phi_g \right\}, sz = s \cdot r$$
 10.9

where s is the excitation error, which quantifies the deviation from the exact Bragg condition and when $sz = s \cdot r \neq 0$, there is diffraction contrast. The scattering amplitude of the diffraction contrast can be calculated by solving Schrödinger's equations.

$$\phi_g = \frac{\pi a i}{\xi_g} e^{2\pi i \mathbf{K} \cdot \mathbf{r}_a} e^{2\pi i \mathbf{k}_g \cdot \mathbf{r}}$$
 10.10

The total wavefunction in the two-beam condition is given by,

$$\Psi_T = \phi_0 e^{2\pi i \mathbf{k}_0 \cdot \mathbf{r}} + \phi_{a1} e^{2\pi i \mathbf{k}_{g1} \cdot \mathbf{r}} + \phi_{a2} e^{2\pi i \mathbf{k}_{g2} \cdot \mathbf{r}} + \phi_{a3} e^{2\pi i \mathbf{k}_{g3} \cdot \mathbf{r}} \dots$$
 10.11

In the 2-beam condition, only the first two terms are considered. Note that r and s are parallel to z. The scattering amplitudes can be put in terms of γ the phase of the electron beam.

$$\phi_o = C_o e^{2\pi i \gamma z},$$

$$\phi_g = 2\xi_g \gamma C_o e^{2\pi i \gamma z}$$
10.12

When a dislocation is present, the local strain field changes the values of s_R and $\phi_g(z)'$, leading to contrast variations that are crucial for determining the Burgers vector and line direction:

The amplitude of the transmitted beam propagating along z,

$$\phi_o(z)' = \phi_o \exp\left(\frac{-\pi i z}{\xi_o}\right)$$
 10.13

The scattering amplitude of the diffracted beam is phase shifted the lattice translation and distortions produced by a defect and is given as follows:

$$\phi_g(z)' = \phi_g \exp\left(2\pi i s z - \frac{\pi i z}{\xi_o} + 2\pi i \boldsymbol{g} \cdot \boldsymbol{R}(\boldsymbol{r})\right)$$
 10.14

The interaction of these transmitted and diffracted beams in a two-beam condition produces a diffraction contrast around the defect described by the following relation,

$$d\phi_g = \left(\frac{\pi i}{\xi_g}\phi_o(z)' + 2\pi i s_R \phi_g(z)'\right) dz \text{ and } s_R = s + \boldsymbol{g} \cdot \frac{d\boldsymbol{R}(r)}{dz}$$
 10.15

When $\mathbf{g} \cdot \mathbf{R}(\mathbf{r}) = \mathbf{0}$ there is no phase shift and amplitude contrast around the defect, i.e., it is invisible. Since $\mathbf{R}(\mathbf{r}) = \vec{b}$ for dislocation, $\mathbf{g} \cdot \mathbf{b} = \mathbf{0}$ can be used as a criterion for determining the dislocation character. For stacking faults, the fringes appear with distinct patterns related to the crystallography

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of the stacking faults, e.g., intrinsic or extrinsic Frank a/3<111> type stacking fault. See Table 2 and Figure 10-12.

Table 2. Amplitude Contra	ast variation around differen	ent stacking faults under	different two-beam	imaging conditions
1 doic 2. 1 implitude Collar	ast variation around anrier	chi stacking radits ander	different two ocuin	minaging conditions

	R(r)	g	$2\pi g \cdot R$
SF in FCC	$\frac{1}{3}[111]$	(111), (220),(113)	$2\pi/3$
SF in FCC	$\frac{1}{6} [11\overline{2}]$	(111) (220)	$0 \\ 4\pi/3$

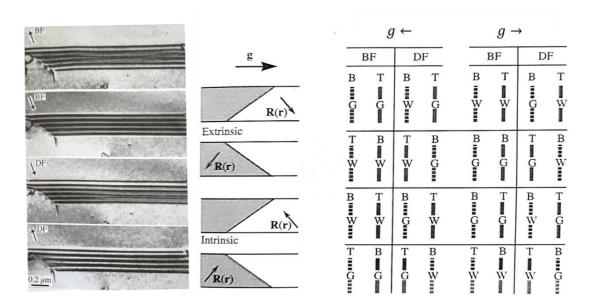
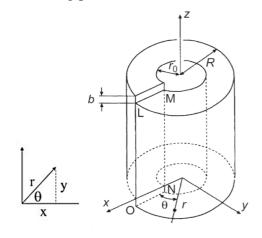


Figure 10-12: A series of brightfield and darkfield TEM images of a Frank stacking fault under different two-beam diffraction conditions. By observing the fringe contrast, the crystallographic properties of this stacking fault can be determined.

For screw dislocation, the invisible criterion follows the radial displacement field due to the Burger's vector being parallel to the dislocation line.



Shear Deformation along z directions on (r,z) plane

$$u_r = u_\theta = 0 \qquad u_z = \frac{b\theta}{2\pi} \tag{10.16}$$

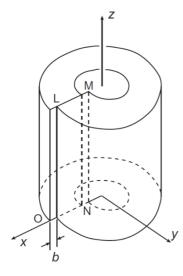
$$R(x,y) = \frac{\mathbf{b}}{2\pi} tan^{-1} \left(\frac{x}{y}\right)$$
 10.17

The contrast extinction condition require

$$\mathbf{g} \cdot \mathbf{R} = 0, \pm 1, \dots \to \mathbf{g} \cdot \mathbf{b} = \mathbf{0}$$

Figure 10-13: Displacement field of a screw dislocation

Since the Burger's vector is perpendicular to dislocation line, the invisible criterion for an edge dislocation is more involved and follows,



Plane Strain of edge dislocation

$$u_z = 0 \qquad u_x = \frac{b}{2\pi} \left(\theta + \frac{\sin 2\theta}{4(1-\nu)} \right)$$
 10.19

$$u_{y} = -\frac{b}{2\pi} \left(\frac{1 - 2v}{2(1 - v)} \ln r + \frac{\cos 2\theta}{4(1 - v)} \right)$$
 10.20

$$\mathbf{R} = \mathbf{b} \frac{\sin 2\theta}{4(1-\nu)} + \mathbf{b} \wedge \vec{\xi} \left(\frac{1-2\nu}{2(1-\nu)} \ln r + \frac{\cos 2\theta}{4(1-\nu)} \right)$$
 10.21

The contrast extinction condition requires

$$g \cdot \mathbf{R} = 0, \pm 1, \dots \to g \cdot \mathbf{b} = \mathbf{0}$$

$$g \cdot (\mathbf{b} \wedge \overline{\xi}) = 0 \dots \to g \parallel \vec{\xi} \cdot \mathbf{b} = \mathbf{0}$$
10.22

Figure 10-14: Displacement field of an edge dislocation

10.3 Characterization of Dislocations Using TEM Imaging Techniques

Three key imaging techniques are used to study dislocations in TEM: brightfield (BF), dark-field (DF), and weak-beam dark-field (WBDF). Each technique exploits the diffraction contrast governed by the Howie-Whelan equations to reveal different aspects of the dislocation structure.

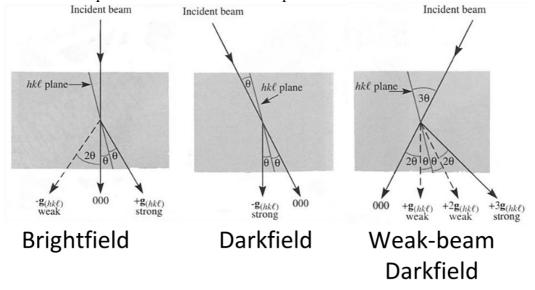


Figure 10-15: Ray diagrams for different imaging modes

10.3.1 Brightfield Imaging

Brightfield imaging is one of the most commonly used TEM techniques for dislocation analysis. In BF imaging, the central transmitted beam is allowed to pass through the objective aperture, and any diffracted beams are excluded. The dislocation contrast in BF images is primarily determined by the page 212

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variation in the intensity of the transmitted beam due to changes in diffraction conditions around the dislocation core.

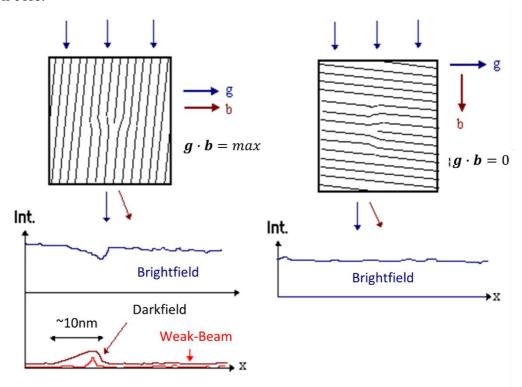


Figure 10-16: Schematic showing how imaging using different two-beam conditions with different \vec{g} vectors, the visibility of dislocation changes due relationship with its Burger's vector.

10.3.2 Dark-Field Imaging

Dark-field imaging is achieved by selecting a diffracted beam (rather than the transmitted beam) using the objective aperture. This technique provides higher contrast for specific features, such as dislocations and stacking faults, compared to brightfield imaging. In DF mode, the diffraction condition plays a critical role in determining whether a dislocation will be visible. That is, the "g·b" criterion applies to DF imaging as well, but in this mode, contrast is often more sensitive to the strain field of the dislocation. DF imaging is particularly useful for imaging edge and mixed dislocations, where strain fields can extend over large areas. Contrast in DF images is primarily influenced by variations in the diffracted intensity due to changes in the local strain field near the dislocation. The contrast formation is similar to BF imaging, but since the diffracted beam is used, small variations in diffraction conditions can produce significant changes in the image contrast.

10.3.3 Weak-Beam Dark-Field Imaging

Weak-beam dark-field (WBDF) imaging is a more advanced technique that enhances the visibility of strain fields around dislocations while minimizing other contrast sources such as thickness fringes. In WBDF, the objective aperture is centered around a diffracted beam under a slightly off-Bragg condition. This condition ensures that only high-order interactions contribute to the image, making dislocation cores and fine details of the strain field more visible.

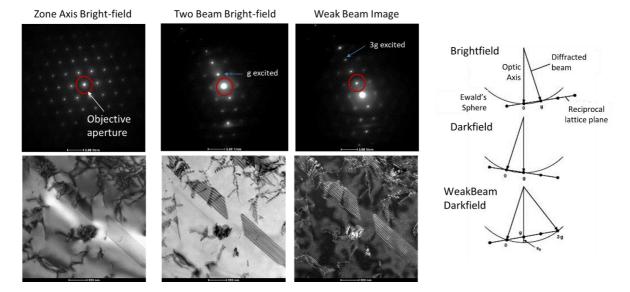


Figure 10-17: Series of imaging under different diffraction condition comparing the width of the diffraction contrast around the dislocation and stacking in FCC intermetallic CoCr alloy.

The contrast in WBDF images is highly sensitive to both \boldsymbol{g} and \boldsymbol{s} , making it ideal for detailed characterization. Note under "kinematical" zone axis and two beam diffraction conditions, the contrast is strong but also spatially broad, blurring details of the dislocation structures. The primary advantage of WBDF over BF and DF is its ability to provide high-resolution images of the dislocation core structure. The enhanced contrast provides for more accurate determination of the Burgers vector and the line direction of the dislocation.

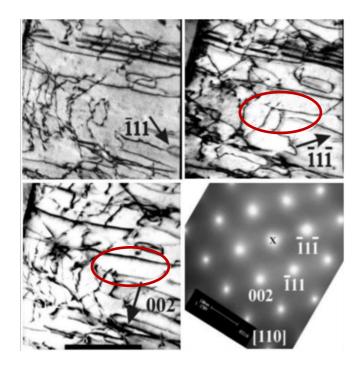
10.3.4 Determination of Burgers Vector and Line Direction

The precise determination of the Burgers vector and line direction is essential for understanding the type and behavior of dislocations in a material. The Burgers vector characterizes the magnitude and direction of lattice distortion caused by the dislocation. By using a combination of BF, DF, and WBDF techniques, it is possible to determine \vec{b} and the line direction $\vec{\xi}$ with high accuracy. The so-called " $g \cdot b$ criterion", where \vec{g} is the diffraction vector and \vec{b} is the Burgers vector, is used to determine whether a dislocation will be visible:

- A dislocation will appear in BF imaging with maximum constrast if $\vec{g} \parallel \vec{b}$.
- When $\mathbf{g} \cdot \mathbf{b} = \mathbf{0}$, no contrast is observed.
- If it is an edge dislocation, no contrast must also observed $\mathbf{g} \cdot \mathbf{b} \wedge \mathbf{\xi} = \mathbf{0}$

Using this criterion, BF imaging can be employed to identify the Burgers vector of a dislocation by selecting different diffraction conditions and examining which dislocations appear or disappear in the image. To apply this method:

- Select a series of diffraction conditions using different diffraction vectors \vec{g} .
- Record images under each condition and note which dislocations are visible.
- Use the visibility rules: a dislocation will only appear if $g \cdot b = 0$, and find at least two g_1 and g_2 that meet this criterion.
- By systematically varying \vec{g} and observing contrast changes, the components of \vec{b} and the line direction $\vec{\xi}$ can be determined.



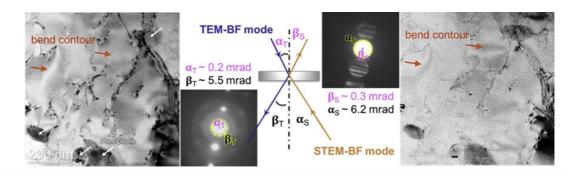
\boldsymbol{g}	b	$g \cdot b$	$g \cdot b \wedge \vec{\xi}$
	1/2[110]	0	≠ 0
[111]	$1/2[0\overline{1}1]$	0	≠ 0
	1/2[101]	0	≠ 0
	$1/2[1\overline{1}0]$	-1	≠ 0
[111]	1/2[011]	-1	≠ 0
	$1/2[10\overline{1}]$	-1	≠ 0

Possible Burger's vectors $[0\overline{1}1]$ and [101]

Figure 10-18: An example dislocation analysis. The montage on the left shows a series TEM brightfield images taken under different two beam conditions \vec{g} vectors. The red elipses mark dislocations invisible with $\vec{g} = [\bar{1}11]$ but visible with $\vec{g} = [\bar{1}1\bar{1}]$, [002]. Using the table on the right, these dislocations must have Burger's vector of [0 $\bar{1}1$] or [101].

10.4 Scanning TEM dislocation imaging

In STEM, a finely focused electron beam is rastered over the sample, enabling a detailed analysis of local atomic structure, chemistry and electronic structure as discussed in section 10.2.3. STEM imaging modes, including high-angle annular dark-field (HAADF) and brightfield STEM, are particularly suited for imaging dislocations. Compared to conventional TEM imaging, diffraction contrast imaging scanning transmission electron microscopy with appropriate setting can provide better defect contrast with almost negligible bend contour artifacts, enabling more effective analysis of dislocation structures. One main advantage of STEM imaging is that bend contours, which commonly obscure underlying defect structures. For good diffraction contrast conditions, the electron microscope parameters for STEM imaging must strictly comply with the principle of reciprocity such that STEM probe convergence angle, α_{S} , is similar to the collection angle (the size of the objective aperture) for brightfield TEM imaging, β_{T} , on the order of 5mrad. Having the STEM imaging mode convergence and collection semi-angles, α_{S} and β_{S} , a few milliradians in size is essential for bend-contour-free defect imaging. This conditions can properly set by adjusting the camera length and using the appropriate STEM detectors.



Bend Contour contrast is suppressed when $\beta_S \approx \alpha_S$

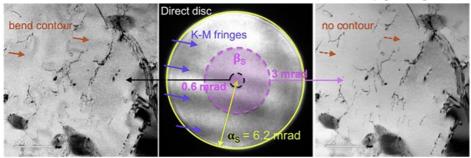


Figure 10-19: Upper montage of images show that having STEM probe converenge angle similar to the TEM brightfield collection angle provides good diffraction contrast. The lower series of imagies demonstrate that when the probe convergence angle and collections are similar and on the order of few milliradains, bend contours are suppressed.

10.4.1 High-Angle Annular Dark-Field (HAADF) Imaging:

HAADF is one of the most widely used STEM modes for dislocation analysis. In HAADF STEM, electrons scattered at high angles are collected, producing images where contrast is roughly proportional to the atomic number (Z-contrast). This technique provides atomic-resolution images where heavier elements appear brighter, which is useful in heterogeneous materials.

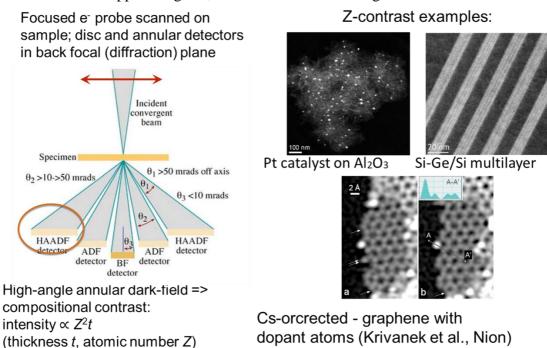


Figure 10-20: Left image is schematic ray diagram of HAADF STEM image. The series of HAADF STEM images on the right demonstrate image contrast arising from differences in the atomic number.

HAADF imaging can directly visualize the core structure of dislocations, including both edge and screw dislocations, by highlighting the distortions and extra half-planes of atoms around the dislocation line. Since HAADF imaging is sensitive to atomic structure and strain fields, it allows researchers to identify the Burgers vector, a key parameter that describes the magnitude and direction of a dislocation. Moreover, the probe converenge and collections angles in aberration corrected HAADF STEM imaging are similar can suppress the bend contour contrast as shown in Figure 10-21 a). The $\mathbf{g} \cdot \mathbf{b} = \mathbf{0}$ criterion also applies to HAADF image. By tilting to specific zone axis, the atomic structure of the care can be observed with aberration corrected high resolution STEM, as souwn in

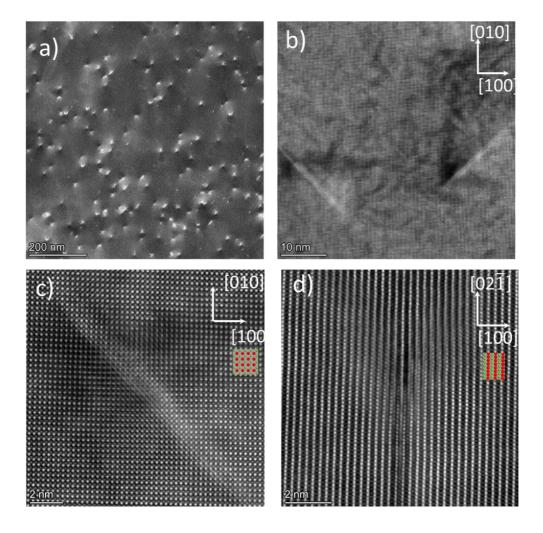


Figure 10-21: a) Low magnification HAADF STEM of misfist dislocations in epitaxial FeRh films grown MgO substrates. Image acquired with $\beta_S(24mrad) \approx \alpha_S(20mrad)$. b) High magnification HAADF image of pair of a<111> type screw dislocation lying on inclined {110} planes of B2 (BCC) FeRh. c) Atomically resolved image of a screw misfit dislocation. d) atomically resolved image of a[100] type misfit edge dislocation in the FeRh film.

10.4.2 Fourier Filtering

Fourier filtering can help visualize the dislocation character and core structure. A fast fourier transform (FFT) of image is performed and spatial frequency related to the lattice distortions are displacements are selected and masked, and inverse fourier transform is taken of masked FFT, as shown in Figure 10-22.

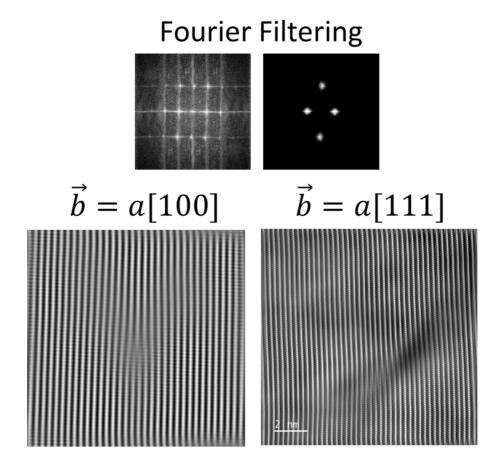


Figure 10-22: Upper images are FFT and masked FFT <200> reflection. Low left is Fourier filter image of a[100] type misfit edge dislocation and right image is a[111} misfit screw dislocation.in an FeRh film shown in Figure 10-21.

10.5 Geometric Phase Analysis (GPA)

Geometric Phase Analysis (GPA) is a technique for quantifying strain fields around dislocations using HRSTEM or HRTEM images and the observed lattice distortions and atomic displacements around dislocations. The application of GPA to dislocations offers key insights into their influence on material behavior. For example, it allows visualization of the displacement fields caused by edge, screw, or mixed dislocations and enables detailed mapping of lattice rotations and distortions near the dislocation core. This capability is critical for studying how dislocations interact with external stresses and other defects. GPA's nanometer-scale resolution and non-invasive nature make it ideal for investigating a variety of materials, including metals, ceramics, and semiconductors, as well as emerging nanostructures. However, the accuracy of GPA depends heavily on the quality of HRTEM images and the proper selection of diffraction spots, as overlapping strain fields or sample preparation artifacts can complicate analysis

GPA provides a quantitative approach to mapping strain (ε) and displacement (u) fields around dislocations by analyzing high-resolution transmission electron microscopy (HRTEM) images in reciprocal space. Dislocations such as screw and edge types induce distinct displacement fields that can be extracted using Fourier transform methods, providing quantitative understanding of the local strain tensor components (u_{xx}, u_{yy}, u_{xy}) and lattice rotations around dislocations.

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Figure 10-23 shows an example of the GPA method. It is essential to caputure high-quality HRTEM images of the crystal region containing the dislocation(s), e.g., Figure 10-23 a. Those images are coverted from real space to reciprocal space using a 2D Fourier transform, which gernerates diffractogram (not true diffraction patterns) with spots corresponding to lattice periodicity (see inset image of Figure xx a). Then, specific diffraction spots (\vec{g}) related to the lattice planes of interest are selected and masked similar to Fourier filtering used to better image the dislocation core, e.g., Figure xx b and $\vec{g}(x,y) = g_x \hat{x} + g_y \hat{y}$. The geometrical phase, $\phi(r)$, associated with those reciprocal lattice frequencies can be extracted considering,

$$\phi(\mathbf{r}) = \mathbf{\vec{g}} \cdot \mathbf{\vec{u}}(\mathbf{r}) \tag{10.23}$$

where $\vec{u}(r) = (u_x + u_y)$ is the displacement field in real space. Displacements are measured by calculating the 'local' Fourier components of the lattice fringe ,e.g, figure xx b. In this formulation, the intensity in an image, I(r), is written as:

$$I(r) = \sum_{q} I_{q}(r) e^{2\pi i q \cdot r}$$
 10.24

where \vec{g} are the reciprocal lattice vectors describing the undistorted lattice. The local Fourier components are obtained by filtering in Fourier space and have an amplitude and phase of,

$$I_g(\mathbf{r}) = A_g(\mathbf{r})e^{iP_g(\mathbf{r})}$$
 10.25

where the amplitude, $A_g(r)$, describes the local contrast of the fringes and the phase, $P_g(r)$, their position. The phase is related simply to the displacement field $\vec{u}(r)$ by the following equation,

$$P_a(\mathbf{r}) = -2\pi \vec{\mathbf{g}} \cdot \vec{\mathbf{u}}(\mathbf{r})$$
 10.26

and by measuring two phase images, $P_{g1}(\mathbf{r})$ and $P_{g2}(\mathbf{r})$, and extracting their amplitude and phase, the two dimensional displacement field can be determined,

$$\vec{u}(r) = -\frac{1}{2\pi} [P_{g1}(r)a_1 + P_{g2}(r)a_2]$$
 10.27

Here a_1 and a_2 are the basis vectors for the lattice in real space corresponding to the reciprocal lattice defined by g_1 and g_2 . The strain components are by differentiating the displacement fields

For a screw dislocation with a Burgers vector \vec{b} parallel to its line vector $\vec{\xi}$ along z:

- The displacement field $u_z(x, y)$ is rotationally symmetric about the dislocation core.
- Strain is distributed tangentially around the dislocation line.

The strain tensor components include,

$$u_{zx} = \frac{\partial u_z}{\partial x}$$
, $u_{xy} = \frac{\partial u_z}{\partial y}$

For an edge dislocation with a Burgers vector \vec{b} perpendicular to its line vector $\vec{\xi}$ along x:

- The $u_{xx}(x, y)$ and $u_{xy}(x, y)$ component dominates.
- Strain fields are concentrated near the dislocation line, with tensile strain above and compressive strain below.

The strain tensor components for an edge dislocation are:

$$u_{xx} = \frac{\partial u_x}{\partial x}$$
, $u_{xy} = \frac{\partial u_x}{\partial y}$, $u_{yy} = 0$

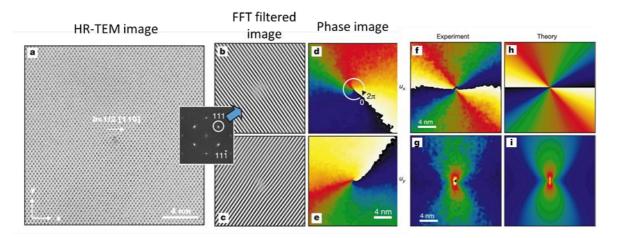


Figure 10-23: a) HRTEM image, b) and c) are Fourier filtered images using the reciprocal lattice spots circled in the inset FFT diffractogram, d) and e) associated phase maps, f) displacement Map showing how atomic planes are shifted around the dislocation, g) strain Maps highlighting regions of tensile, compressive, and shear strain, h) and i) are theoretical calculations of f) and g)

Beyond the quantitative analysis of "static" HRSTEM dislocation imaging, GPA is often complemented by other techniques for more comprehensive insights. In-situ TEM, for example, enables real-time observation of dislocation behavior under external stimuli, while molecular dynamics simulations and finite element methods provide theoretical models for comparison. Machine learning methods are increasingly used to automate GPA workflows, enhancing efficiency and consistency. As a versatile tool for materials characterization, GPA is invaluable for optimizing mechanical properties in advanced materials, improving electronic device performance, and exploring the behavior of defects in low-dimensional systems.

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